

# ***5G/B5G **URLLC** Services and New Opportunities***

Dec. 11, 2017

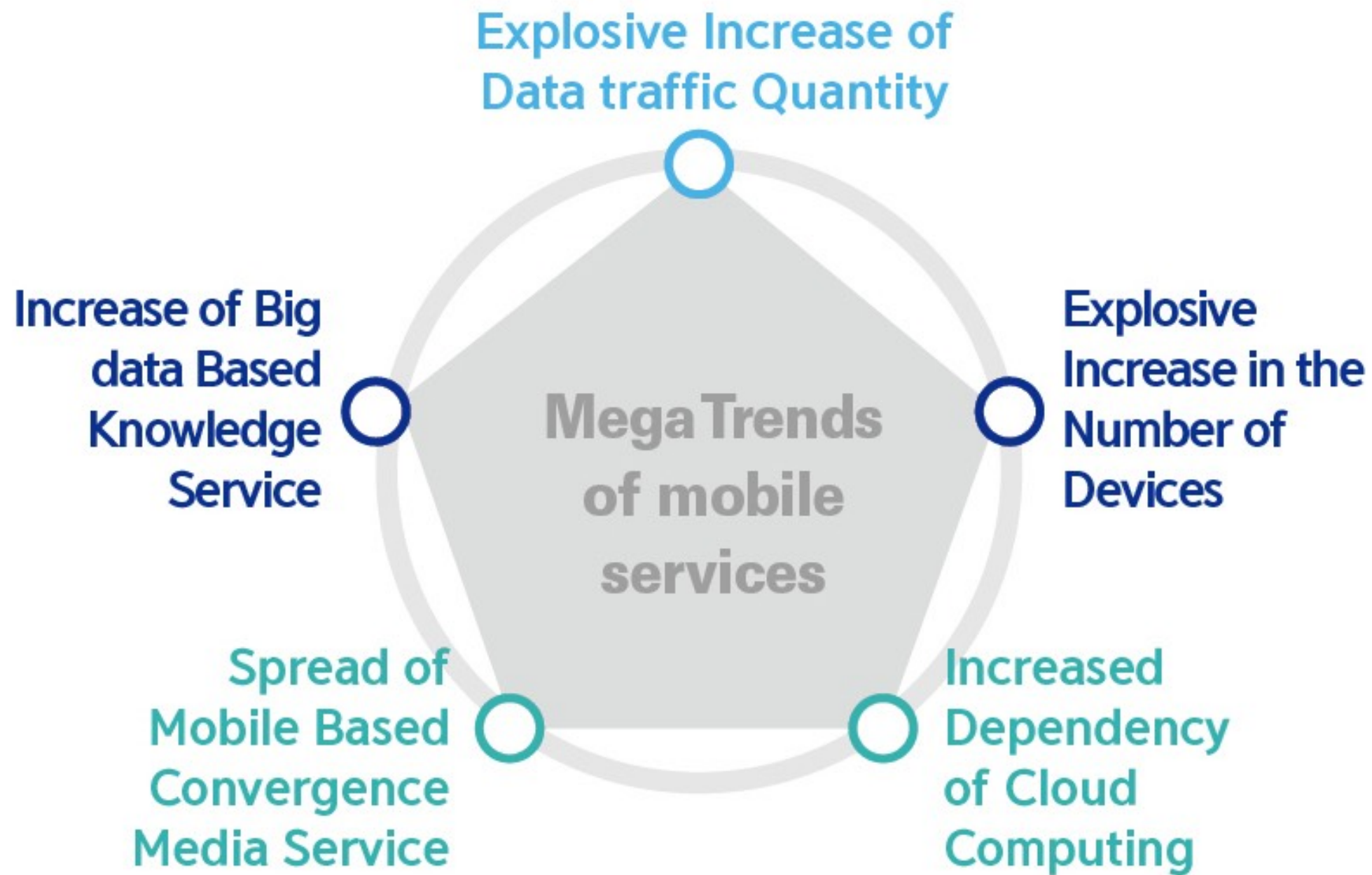
EECE, Hankyong National University  
**Howon Lee**

# ***Outline***

1. Introduction
2. Service Classification
3. URLLC Use-Cases and Requirements
4. URLLC Challenges and Conclusions

# ***Introduction***

# Mobile Service Mega Trends



→ **Five *Golden* Opportunities !!**



# From *INPUT* to *OUTPUT*

PFC: PreFrontal Cortex  
(전전두피질)

PMC: PreMotor Cortex  
(전운동피질)

MC: Motor Cortex  
(운동피질)

LGN: Lateral Geniculate Nucleus  
(외측슬상체)

PIT: Posterior Inferior Temporal Cortex  
(Posterior 하측두피질)

AIT: Anterior Inferior Temporal Cortex  
(Anterior 하측두피질)



**INPUT**

**OUTPUT**

Categorical judgments,  
decision making

Motor command

Simple visual forms,  
edges, corners

Simple visual forms,  
edges, corners

V1~V4: Visual Cortex

Intermediate visual forms,  
feature groups, etc.

High-level object  
descriptions, faces, objects

Retina

To finger muscle

To spinal cord

Categorical judgments,  
decision making

100–130 ms

120–160 ms

140–190 ms

30–50 ms

Retina  
20–40 ms

80–100 ms

60–80 ms

40–60 ms

50–70 ms

70–90 ms

High-level object  
descriptions,  
faces,

To finger muscle  
180–260 ms

To spinal cord  
160–220 ms

**180~260ms**



# From **INPUT** to **OUTPUT**

PFC: PreFrontal Cortex  
(전전두피질)

PMC: PreMotor Cortex  
(전운동피질)

MC: Motor Cortex  
(운동피질)

LGN: Lateral Geniculate Nucleus  
(외측슬상체)

PIT: Posterior Inferior Temporal Cortex  
(Posterior 하측두피질)

AIT: Anterior Inferior Temporal Cortex  
(Anterior 하측두피질)

Categorical judgments,  
decision making

Motor command

Simple visual forms,  
edges, corners

Categorical judgments,  
decision making

140–190 ms

Motor command

Simple visual forms,  
edges, corners

120–160 ms

PMC

MC

**Monkeys can categorize complex visual stimuli very quickly, with reaction times that average 250 to 260ms but that can be as short as 180ms.**

High-level object  
descriptions, faces, objects

descriptions  
faces,

To spinal cord

160–220 ms

To finger muscle  
180–260 ms

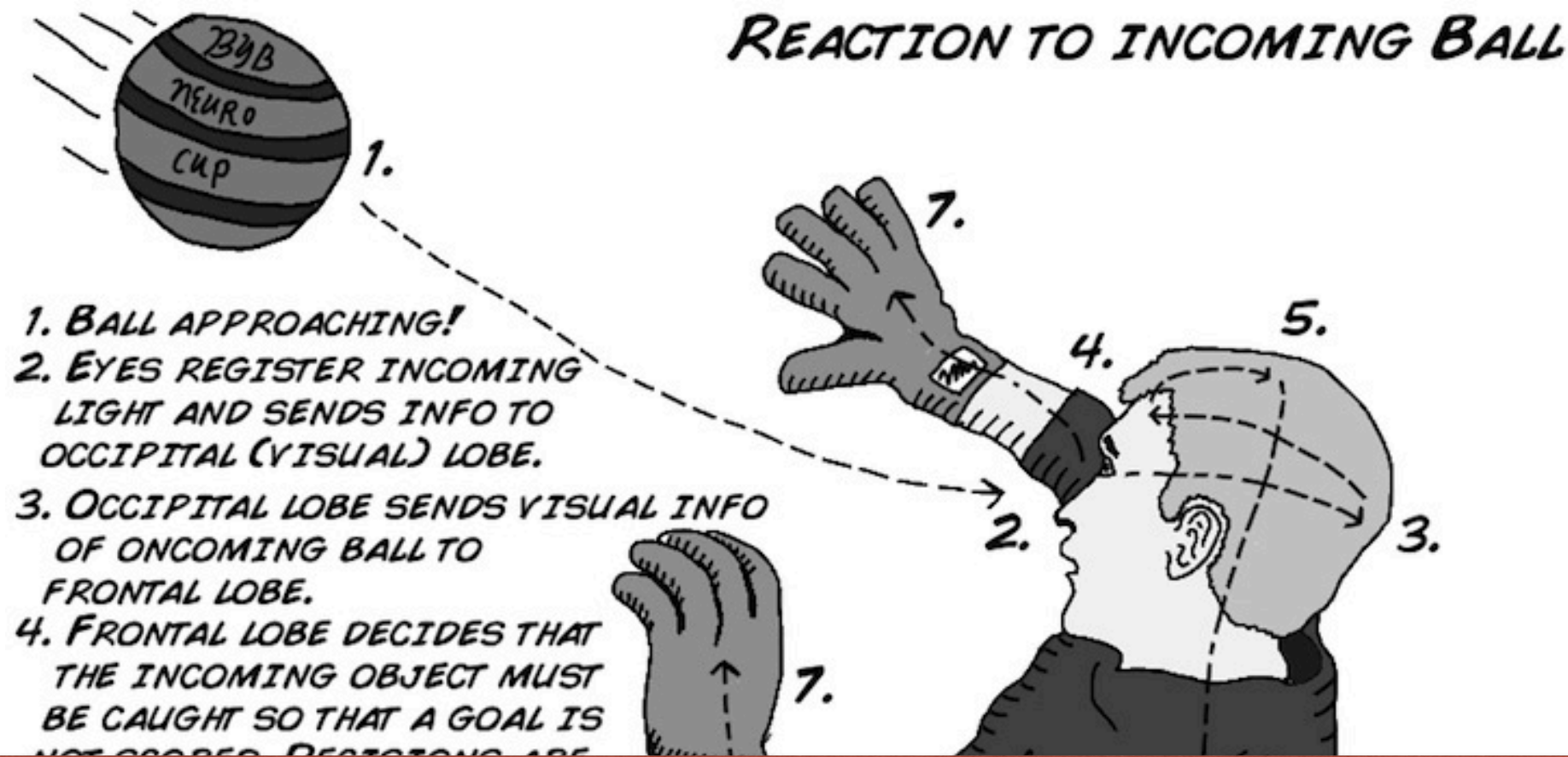
To spinal cord

To finger muscle

**OUTPUT**

**180~260ms**

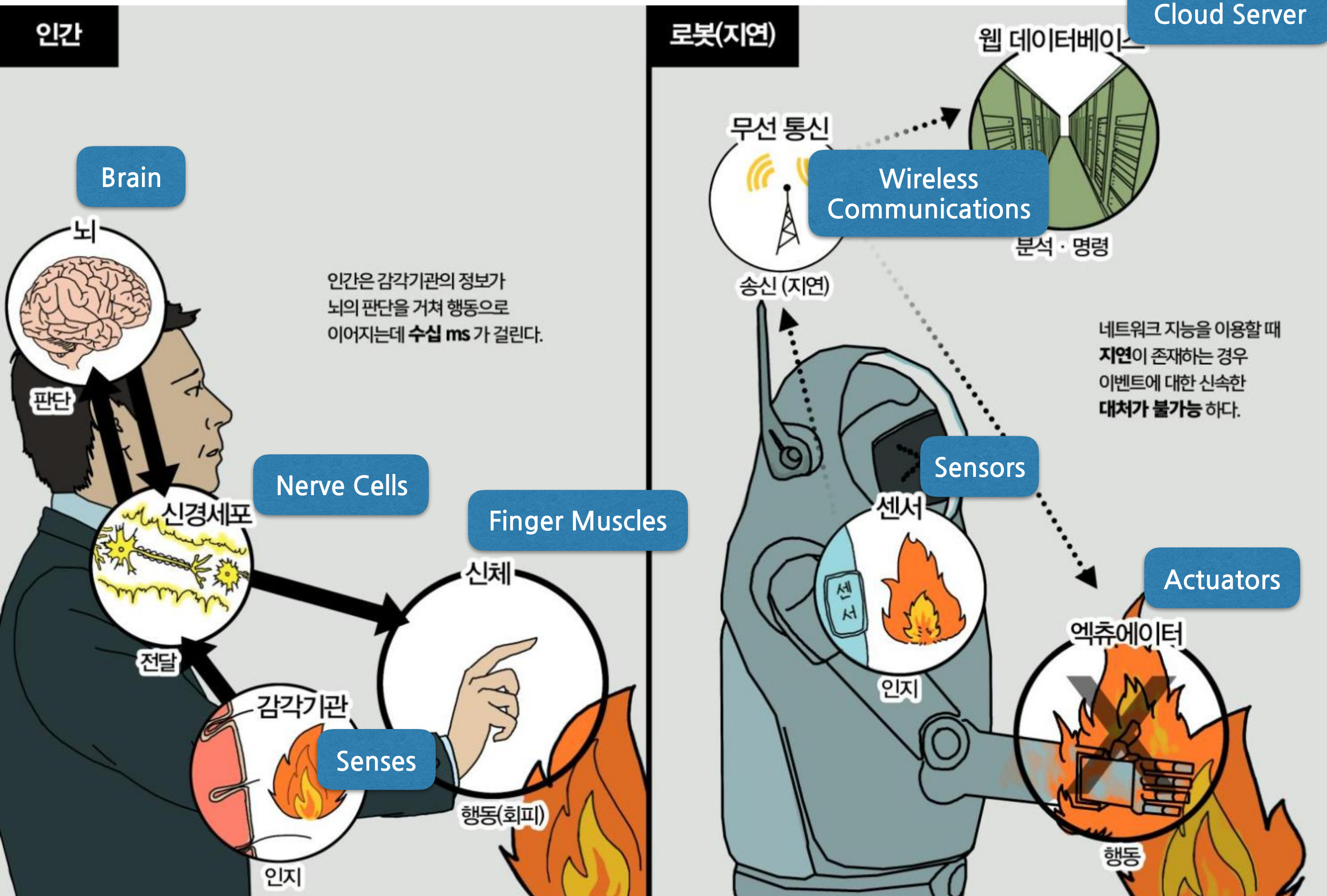
# How Fast Your Brain Reacts to Stimuli



The average reaction time for humans is **250ms** to a visual stimulus, **170ms** for an audio stimulus, and **150ms** for a touch stimulus.



# Human Reaction Mechanism Modeling





# Human Reaction Mechanism Modeling

인간

Brain

뇌

판단

인간은 감각기관의 정보가  
뇌의 판단을 거쳐 행동으로  
이어지는데 수십 ms가 걸린다.

Nerve Cells

신경세포

전달

감각기관

Senses

인지

Finger Muscles

신체

행동(회피)

로봇(초저지연)

무선 통신

Wireless Communications

송수신 (저지연)

웹 데이터베이스

Cloud Server

분석 · 명령

네트워크 지능을 이용할 때  
초저지연이 가능한 경우  
사람 수준의 반사행동이  
가능해진다.

Sensors

센서



인지

엑츠크에이

Actuators

행동(회피)



# ***Service Classification***



# Service Classification

Peak Data Rate: 10 Gbps

Average Data Rate: 50 Mbps

Area Traffic Capacity: 10 Mbps/m<sup>2</sup>

Spectral Efficiency: 15 bps/Hz

## Enhanced Mobile Broadband

Gigabytes in a second

3D video, UHD screens

Work and play in the cloud

Augmented reality

Industry automation

Mission critical application

Self Driving Car

Reliability: 10<sup>-5</sup>

User Plane Latency: 1ms

## Future IMT

## Massive Machine Type Communications

## Ultra-reliable and Low Latency Communications

Connection Density: 1,000,000 devices/km<sup>2</sup>

Control Plane Latency: 10ms

10 years on battery

Smart Home/Building

Voice

Smart City

# Service Classification

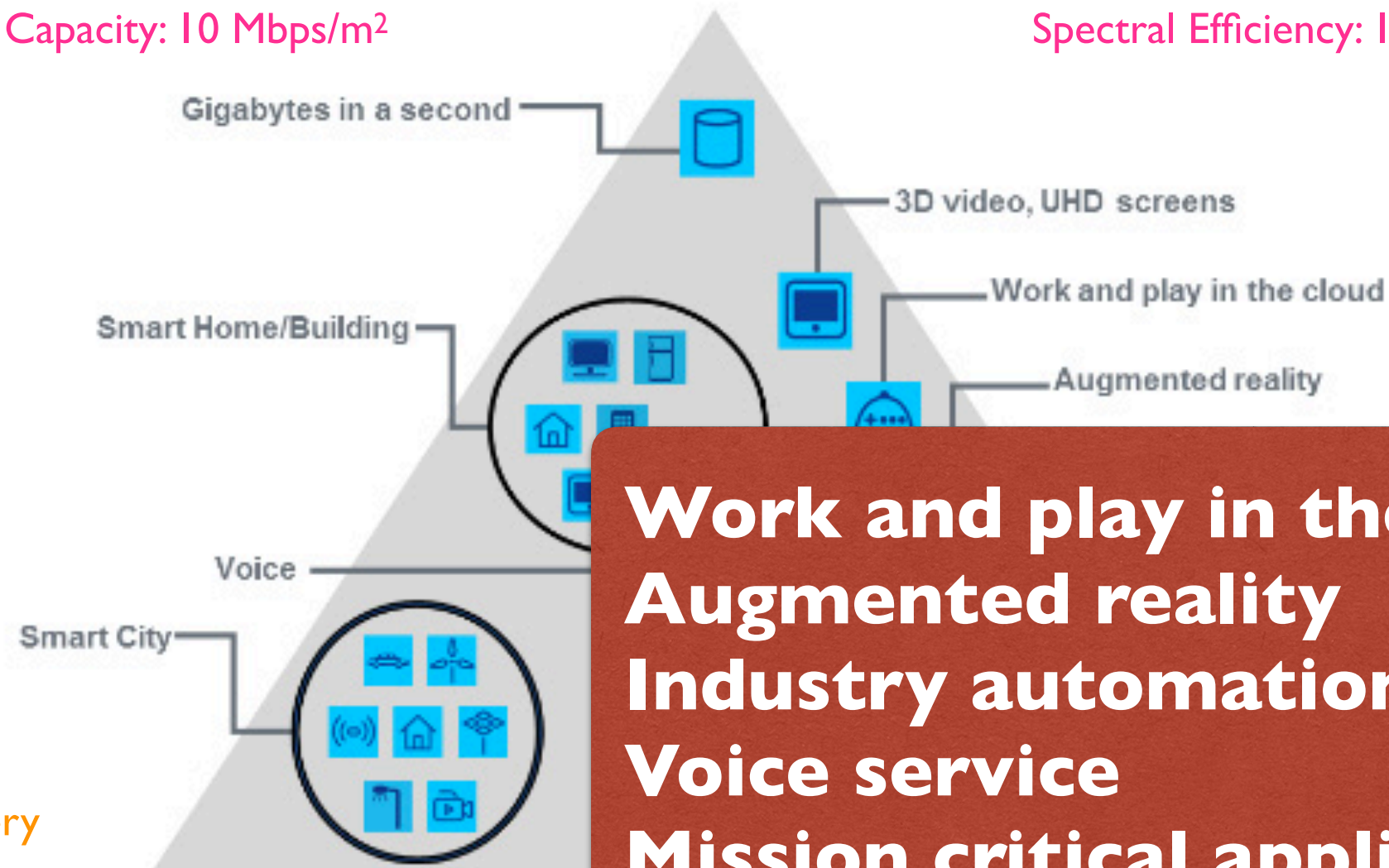
Peak Data Rate: 10 Gbps

Average Data Rate: 50 Mbps

## Enhanced Mobile Broadband

Area Traffic Capacity: 10 Mbps/m<sup>2</sup>

Spectral Efficiency: 15 bps/Hz



10 years on battery

## Massive Machine Type Communications

Connection Density: 1,000,000 devices/km<sup>2</sup>

Control Plane Latency: 10ms

**Work and play in the cloud**  
**Augmented reality**  
**Industry automation**  
**Voice service**  
**Mission critical application**  
**Self driving car**

10<sup>-5</sup>

1ms



# Service Classification

**Intelligent** 지능형 5G 서비스(나를 알아주는...)  
Intelligence

**Immersive**  
몰입형 5G 서비스  
(내가 느끼는...)  
Immersiveness

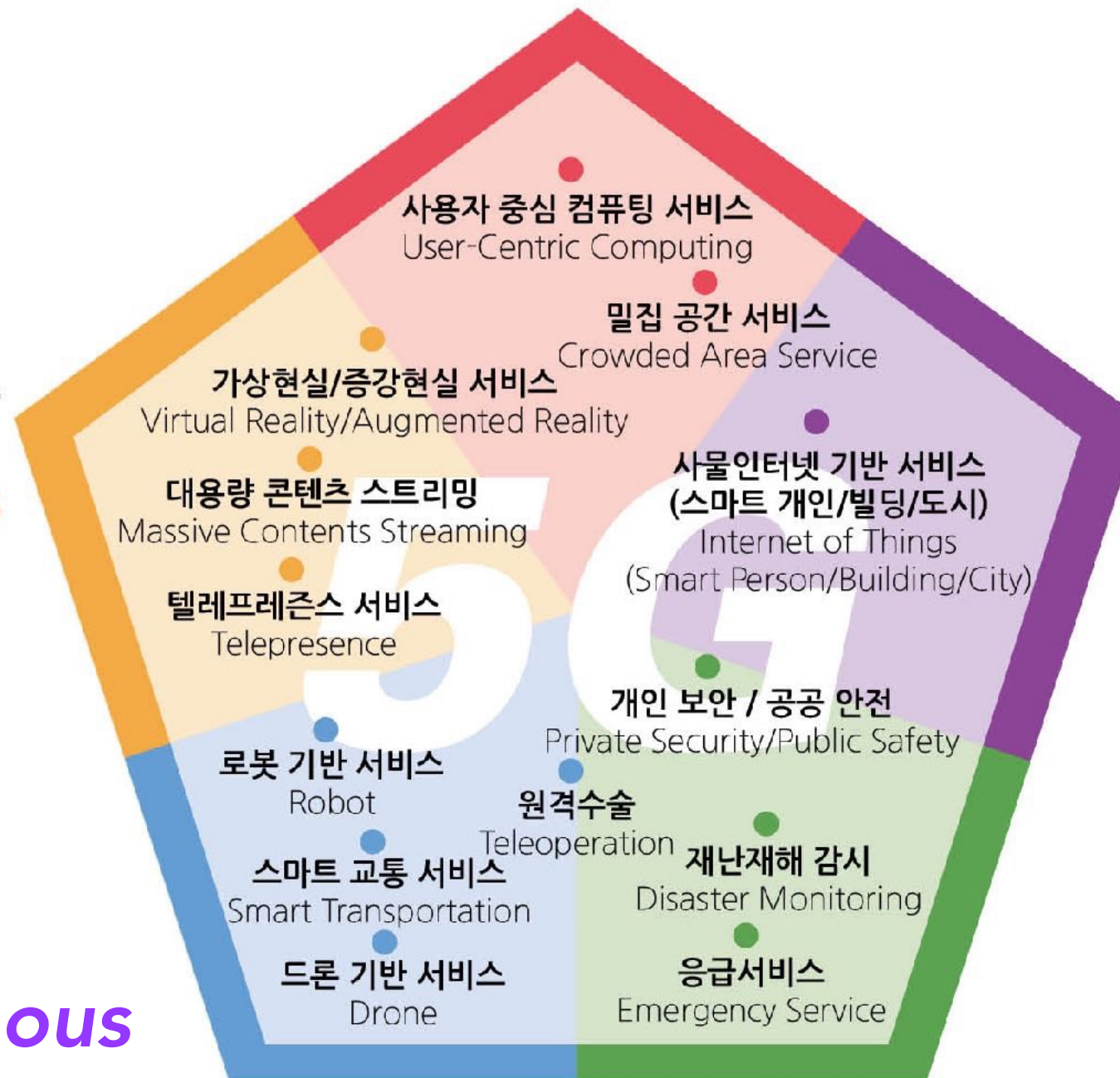
**Omnipresent**  
편재형 5G 서비스  
(나를 둘러싼...)  
Omnipresence

**Autonomous**

**Public**

자율형 5G 서비스(나를 도와주는...)  
Autonomy(Mobility)

공공형 5G 서비스(나를 위한...)  
Publicness



# Service Classification

**Intelligent** 지능형 5G 서비스(나를 알아주는...)  
Intelligence

**Immersive**

몰입형 5G 서비스  
(내가 느끼는...)  
Immersiveness

**Omnipresent**

편재형 5G 서비스  
(나를 둘러싼...)  
Omnipresence

**Virtual reality/Augmented reality**  
**Telepresence**  
**Smart Robot**  
**Smart transportation**  
**Smart Drone**  
**Emergency services**

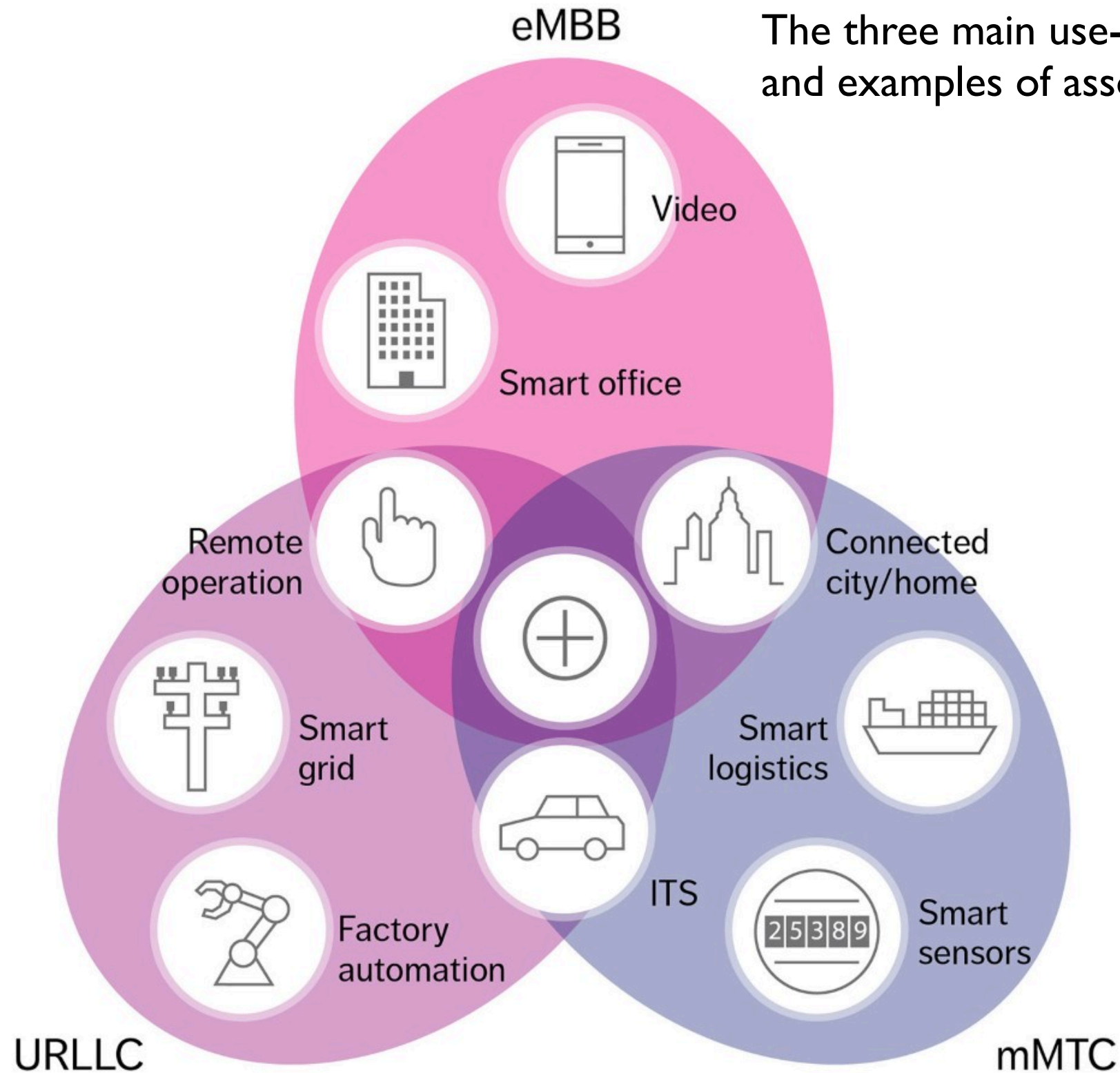
자율형 5G 서비스(나를 도와주는...)  
Autonomy(Mobility)

공공형 5G 서비스(나를 위한...)  
Publicness

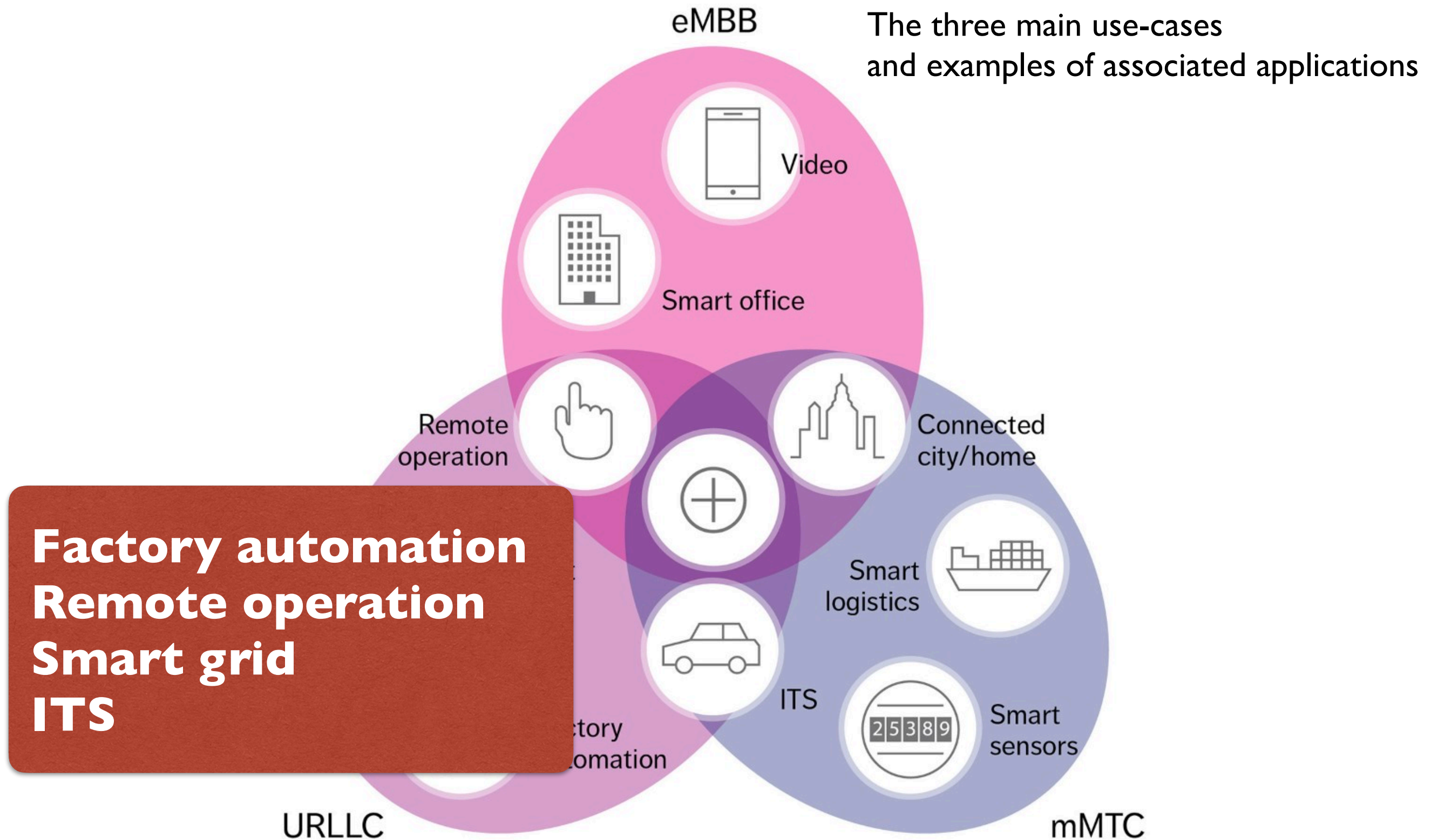
**Public**



# Service Classification

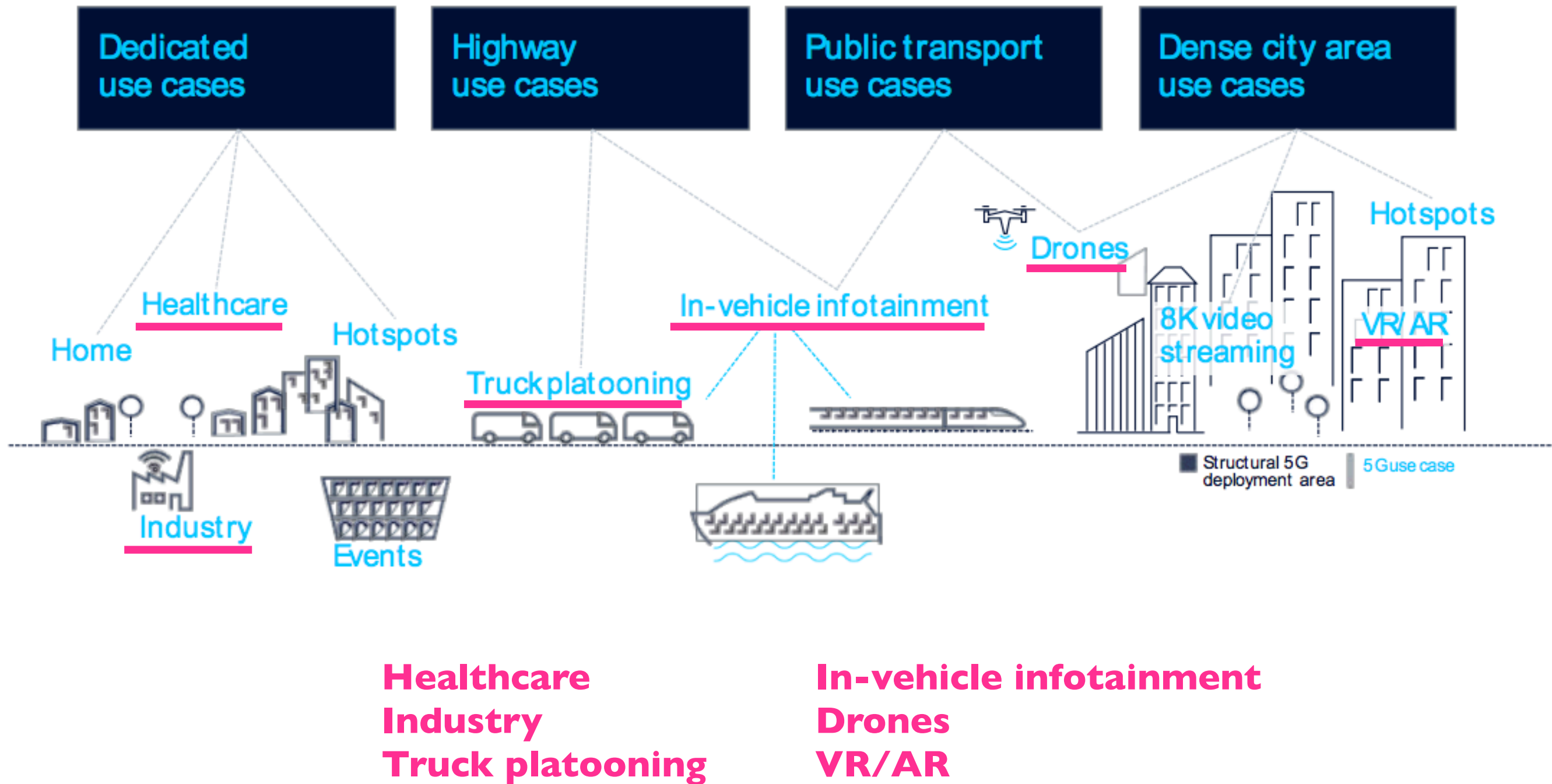


# Service Classification

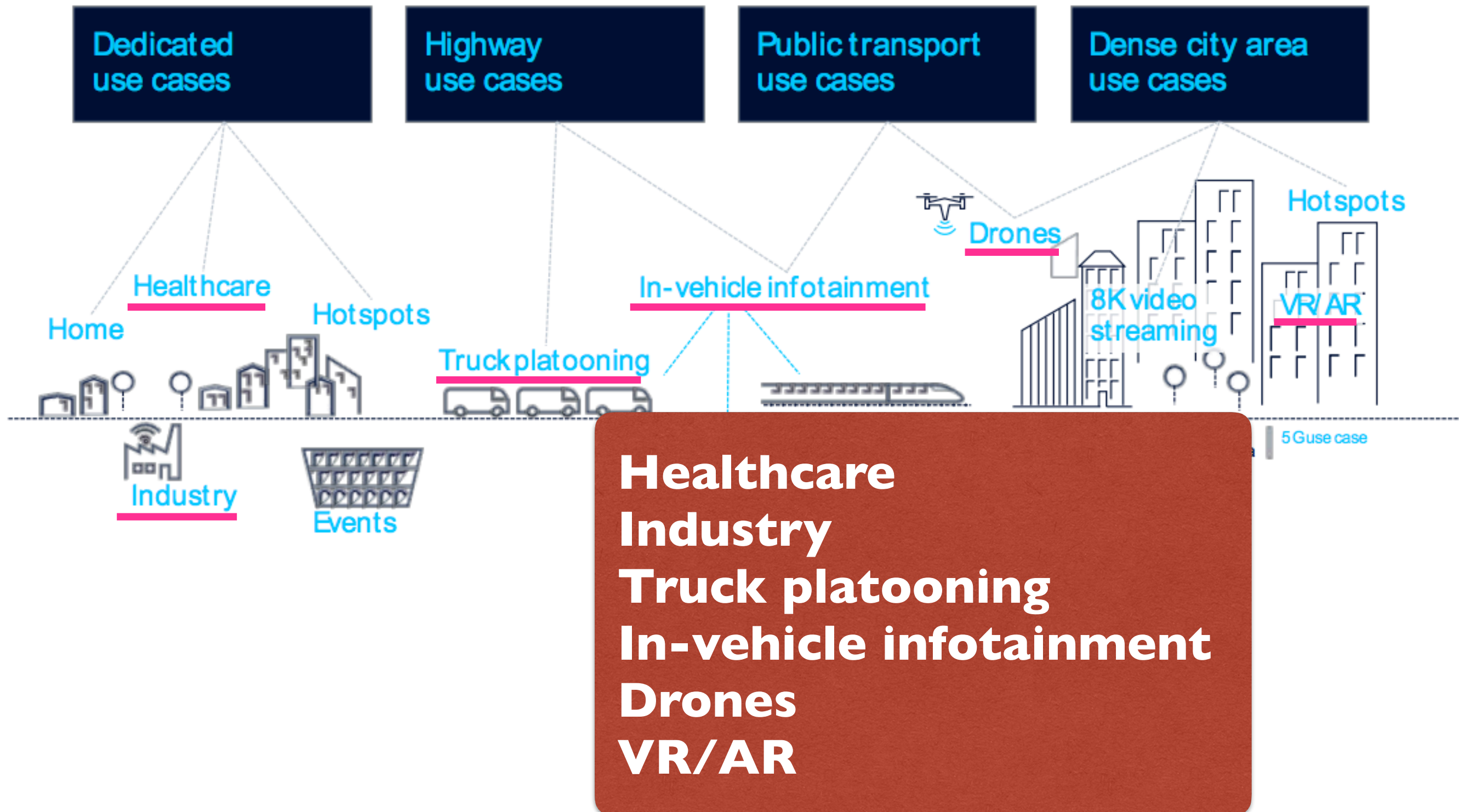




# Service Classification



# Service Classification





# Low-Latency Service Classification

- Telepresence
- Ultra-Fast Touch Response
- Realistic gaming
- Mobile virtual office
- Virtual Reality with Tactile Feedback

Reality via Networks: *Enhanced Delay*

Control via Networks: *Absolute Delay*

**Absolute**

- Traffic Control
- Traffic Safety
- Teleprotection
- Platooning of Vehicles
- Intersection
- SCPR
- Personal Blackbox

**Ultra-Low  
Latency**

Competition via Networks: *Relative Delay*

- Ultra-Low Latency Gaming
- Algorithmic Trading
- Course Registration

**Relative**

**Enhanced**

## Summary

Enhanced - Reality





Absolute - Control

Relative - Competition

# ***URLLC Use-Cases and Requirements***



# URLLC Use-Cases and Requirements

Industry Vertical	Application
Healthcare Industry	 <ul style="list-style-type: none"><li>Remote robotic surgery with haptic feedback</li><li>Remote diagnosis with haptic feedback</li><li>Emergency response in ambulance</li></ul>
Transport Industry	 <ul style="list-style-type: none"><li>Driver assistance applications</li><li>Enhanced safety</li><li>Self-driving cars</li><li>Traffic management</li></ul>
Entertainment Industry	 <ul style="list-style-type: none"><li>Immersive AR/VR services</li><li>Online gaming</li></ul>
Manufacturing Industry	 <ul style="list-style-type: none"><li>Motion control</li><li>Remote control with AR applications</li></ul>

# URLLC Use Cases

- **Remote healthcare and medical intervention (1/2)**

- In past tele-surgery trials with ***no use of haptic feedback***, mentors can compensate delays up to 700ms in less interactive scenarios, while in more interactive mentoring scenarios a shorter delay of up to 250ms is required.

- In the context of tele-surgery, real experiments have determined that the maximum tolerable delay is 150ms.

(Source: P. Dasgupta'03)



(Source: Tele-Visual Infolink)



# URLLC Use Cases

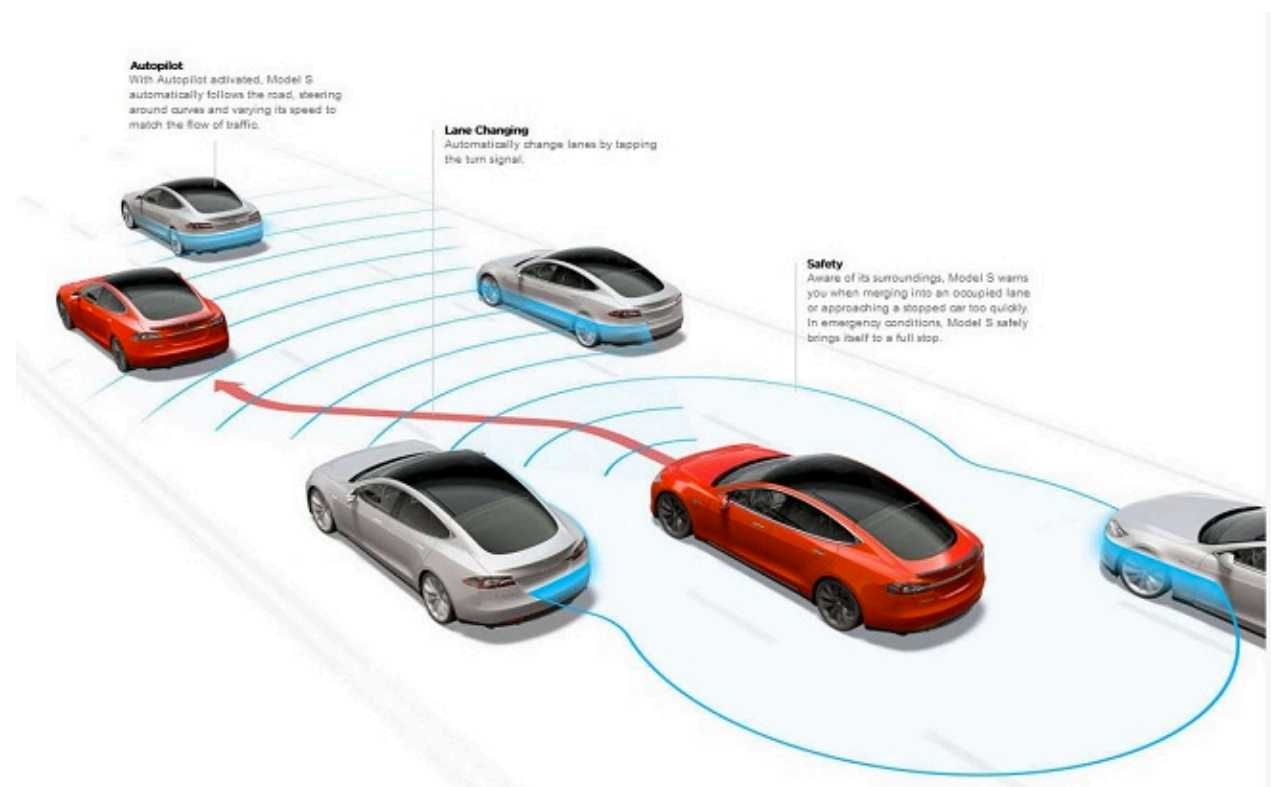
- **Remote healthcare and medical intervention (2/2)**
  - Since there's no haptic feedback included in the previous delay requirement, the reported delays here are all just one way delay.
  - However, ***haptic feedback*** in remote surgery and diagnosis scenarios can increase the accuracy in detection of nodules.
  - Adding the haptic feedback, however, tighten the requirements<sup>결절</sup> on latency, since kinesthetic devices work in closed control loops and the two ends (action and reaction) should operate synchronously with each other.
  - ***So, tele-surgery in the presence of haptic feedback requires end-to-end round trip times (RTTs) of lower than 10ms.***

# URLLC Use Cases

- **Assisted driving and transport services (1/3)**

- Intelligent Transport Systems

- ITS refers to the use of IT, sensors and communications in transport applications, ***aiming at providing more efficient movement and seamless journeys for people.***
  - Automated overtaking systems require a maximum tolerable end-to-end latency of approximately ***10ms on each message exchange.***

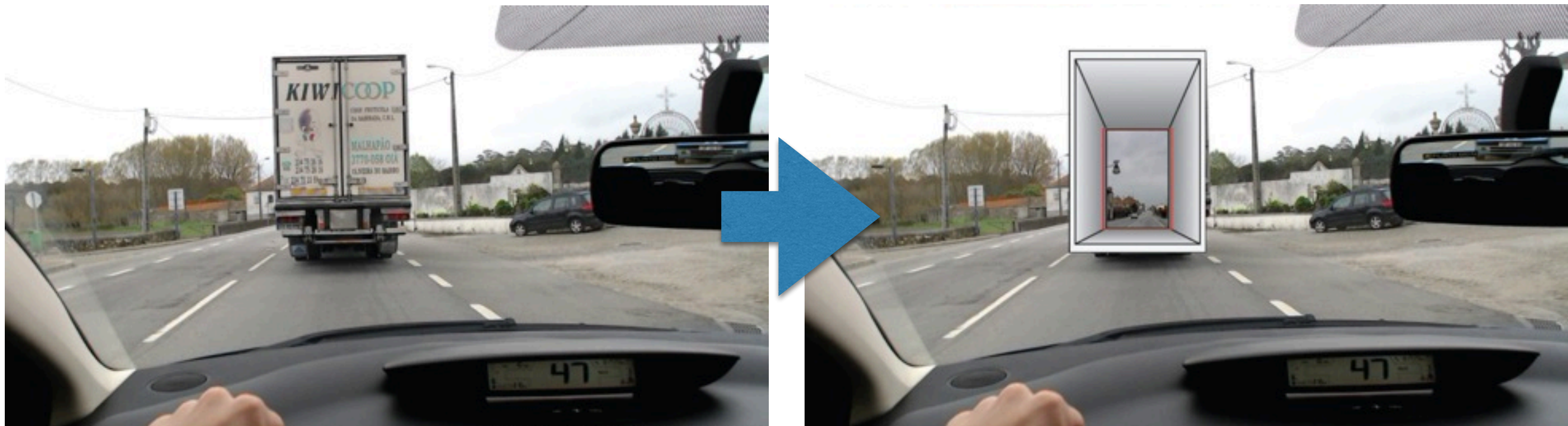


(Source: TeslaMotors)



# URLLC Use Cases

- **Assisted driving and transport services (2/3)**
  - When video is integrated as in the see-through application, encoding and decoding video would suppose prohibitive delays, thus very high data rates low latency are required to transmit real-time raw video.
    - For a 30 frames per second video feed, a capacity of 220Mbps and an end-to-end latency of 50ms shall be supported.



< See-through Application >

# URLLC Use Cases

- **Assisted driving and transport services (3/3)**

- ✓ **Low**-level data (video streaming) transmissions in V2X

- Low-level data generated **by sensors (cameras, lidars, etc.)** is transmitted towards neighboring users (vehicles, infrastructure, tec.) to be fused and/or processed by the receiving system, in conjunction with its own sensors.
- Network requirement: high data rate (up to 10-20 Mbps) with a medium tolerance on errors ( $10^{-2}$ )

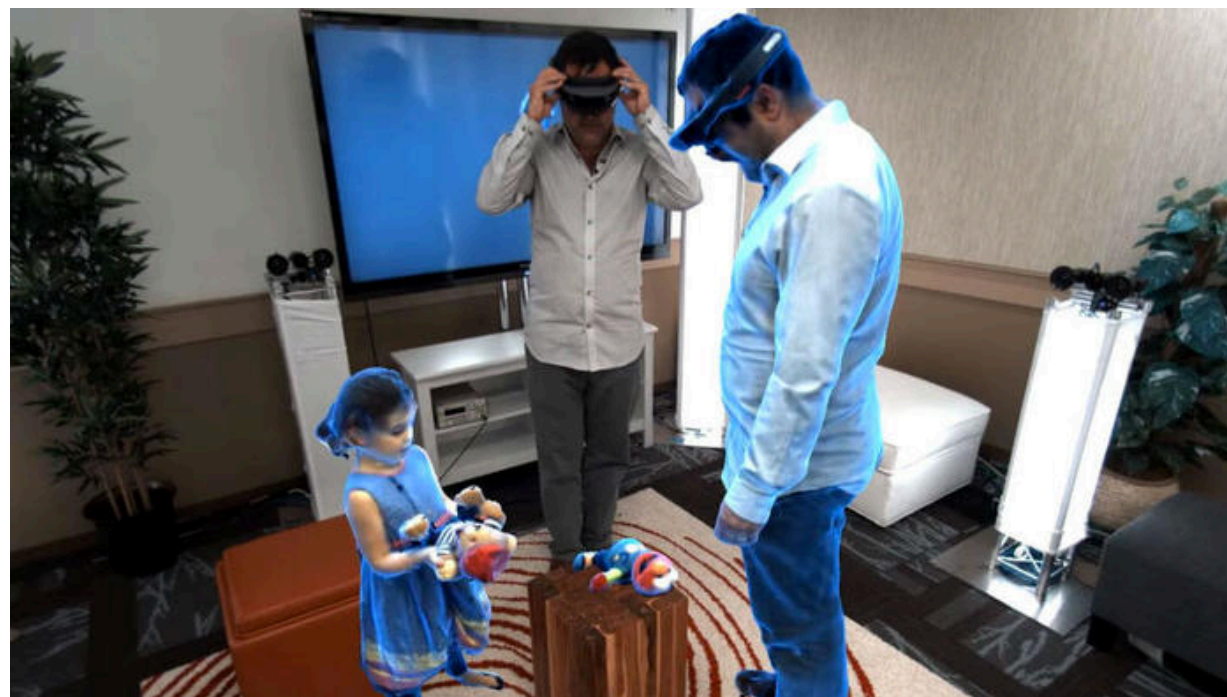
- ✓ **High**-level data (objects) transmissions in V2X

- High-level data generated **after sensor processing (object recognition, Radar or LiDAR target lists)** is transmitted to neighboring users (vehicles, infrastructure, etc.) to be fused by the receiving systems in conjunction with its own sensors.
- Network requirement: medium data rate (up to 1 Mbps) with a very low tolerance on errors ( $10^{-5}$ )



# URLLC Use Cases

- **Entertainment: content delivery and gaming (1/2)**
  - An ultra-reliable low latency network capable of providing the fully immersive multi-sensorial services, through video, audio and tactile can further enhance the consumer experience, in both content delivery and gaming
  - For virtual reality and augmented reality, 7~15ms application to application delay, i.e., action to reaction, is the threshold to provide a smooth action-reaction experience
  - To reduce the processing burden in the device end, 5G should integrate high processing in mobile edge computing clouds



(Source: Microsoft)

# URLLC Use Cases

- **Entertainment: content delivery and gaming (2/2)**
  - Visual interaction
    - Response time within **5ms** is required for tracking the change of viewpoint.
    - Latency within **5ms** is required to synchronize to human movements
  - Auditory interaction
    - Less than **50ms** delay is required to synchronize to visual changes
  - Tactile interaction
    - Less than **1ms** delay is required to prevent cyber sickness
      - : **Cyber sickness** is a condition in which a disagreement exists between visually perceived movement and the viewing movement via mobile/electronic devices.



# URLLC Use Cases

- **Industry automation**

- To digitise the industry to provide higher value products and processes by intelligent networking of product development and production, logistics and customers
- Time critical process optimization and control → Latencies in these use-cases may go below 1ms
  - Realtime optimization based on instantly received information from monitoring or interaction between different operators
  - Remote control robotic operations
  - Collaborative robots in closed-loop control systems.



(Source: Starship Groove)

# URLLC Service Requirements

Industry Vertical	Requirements	Value
Healthcare	<ul style="list-style-type: none"> <li>Robotic tele operations (surgery or remote control of robots in any other application) that require haptic information feedback need to have stable latencies that are below the round trip values of 10ms</li> </ul>	<b>RTT 10ms</b>
Automotive	<ul style="list-style-type: none"> <li>10ms one way delay in cooperative driving</li> <li>Safety related applications in the automotive industry require end-to-end delay as little as 10ms</li> <li>36m cars with SIM cards to be sold by 2018</li> </ul>	<b>E2E 10ms</b>
Entertainment	<ul style="list-style-type: none"> <li>As low as 7ms round trip delay to support VR/AR for supporting a full immersive experience</li> </ul>	<b>RTT 7ms</b>
Manufacturing	<ul style="list-style-type: none"> <li>Sub 1ms one way delay in control applications</li> <li>Cyber-physical systems to play primary role</li> </ul>	<b>OW 1ms</b>

(Source: M. Dohler'17)



# ***URLLC Challenges and Conclusions***

# End-to-End Latency in 5G Networks

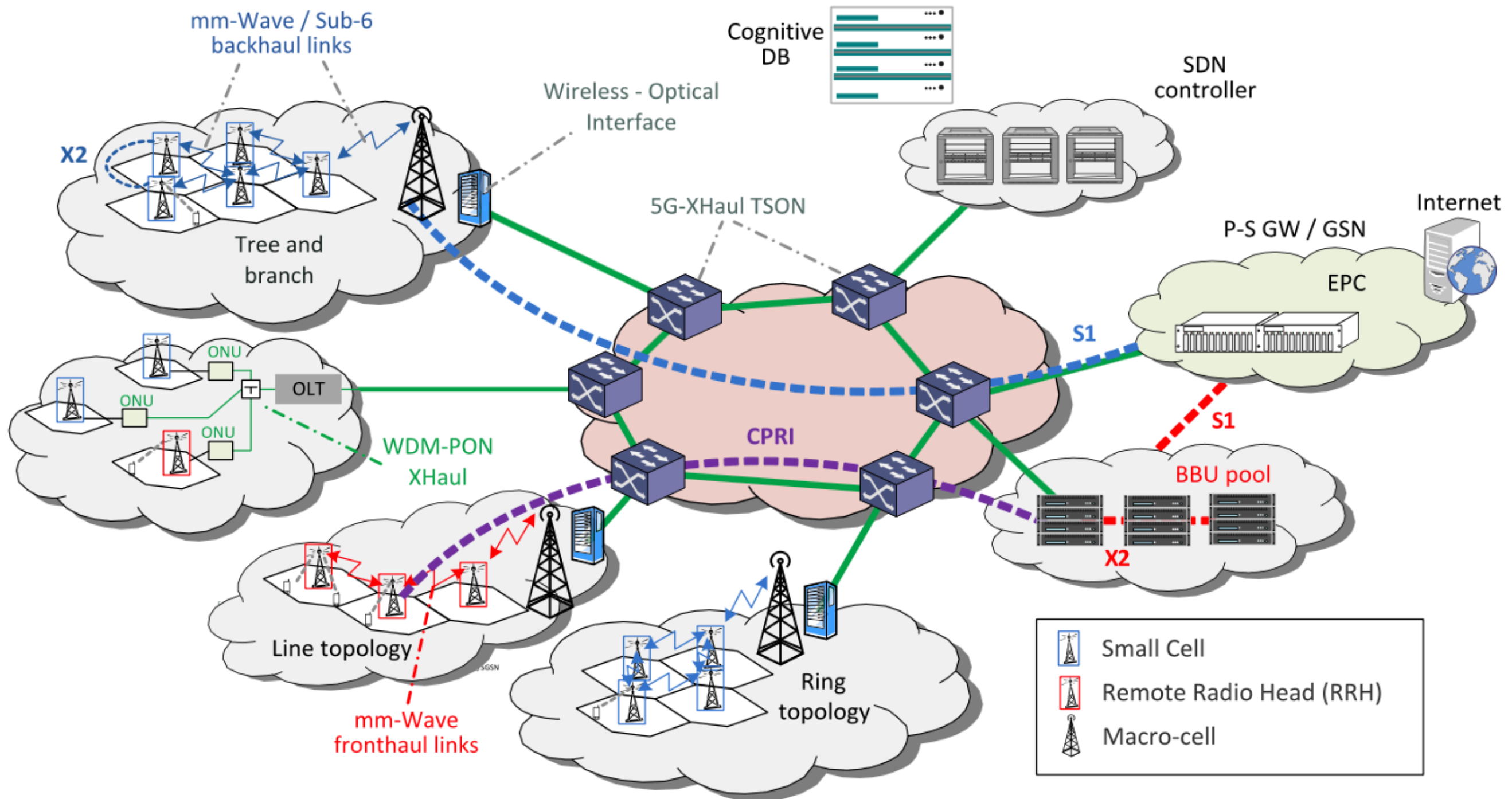


Figure 1.1: 5G-XHaul Network Deployment



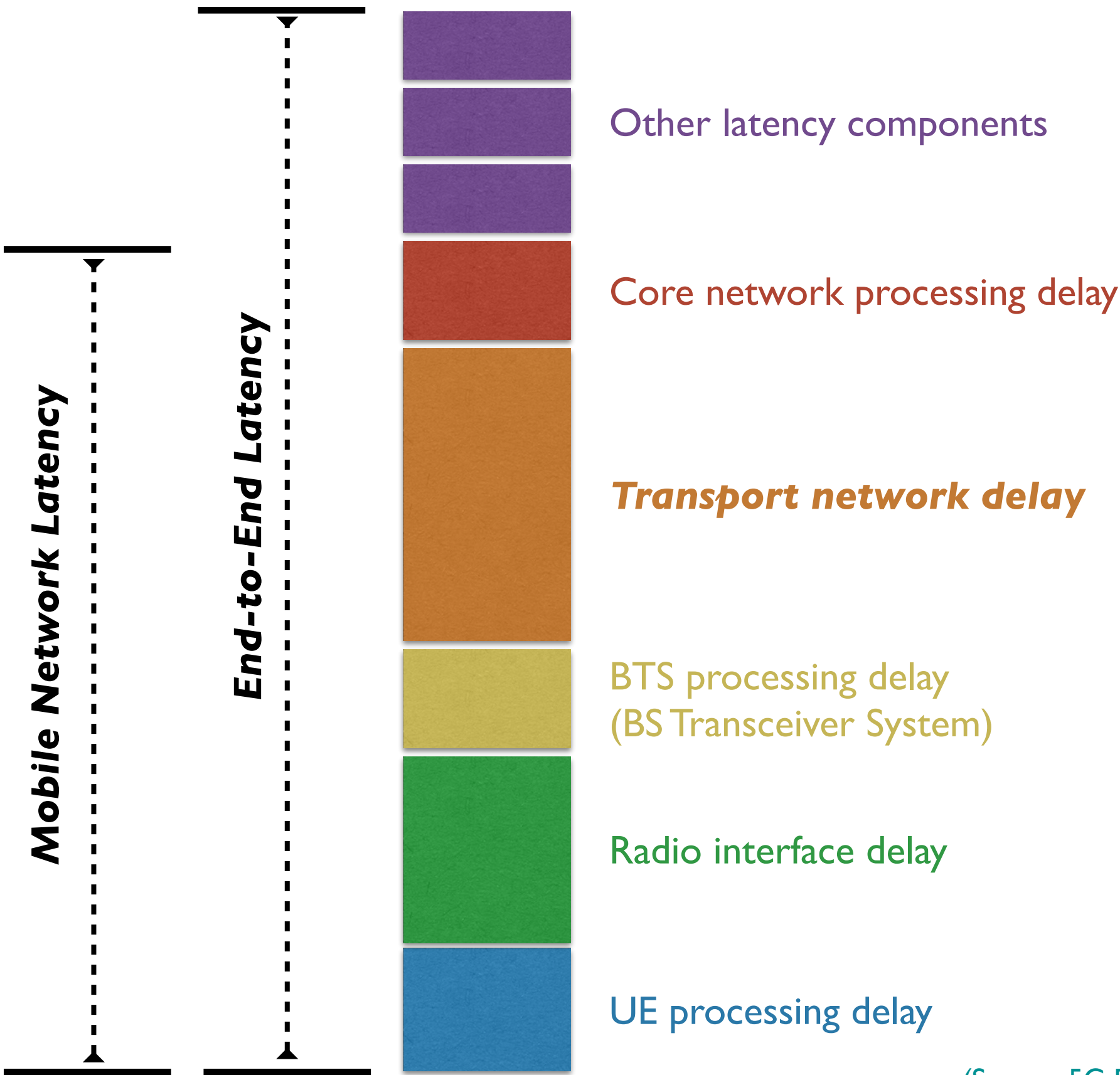
# End-to-End Latency in 5G Networks

Dynamic resource allocations

Mobile edge computing

Higher data rates

Functional split  
(CP/UP, RU/DU)



# End-to-End Latency in 5G Networks

Dynamic resource allocations

Mobile edge computing

Other latency components

**Although many researchers focus on reducing just air interface delay, it is only a small fraction in overall end-to-end latency from the end-users's perspective.**

**Depending on the characteristics of each URLLC use case, the overall end-to-end latency should be reduced.**

UE processing delay



***Thank you.***

([hwlee@hknu.ac.kr](mailto:hwlee@hknu.ac.kr))